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// The Pseudo Code of the Ray-Phong Tessellation Intersection Test
Binary PhongTessellation::Intersect( Ray &ray, Real &depth, Vector3D &barycentric_coord ) const
{
    Real param;
    Real A, B, C, D, E, F;
    Real la1, lb1, lc1, la2, lb2, lc2;
    Real u, v, w;
    Real g, h;
    Real c0, c1, c2;
    Real discriminant, sqrt_discriminant;

    const Vector3D &T1 = ray.PlaneNormal1;
    const Vector3D &T2 = ray.PlaneNormal2;

    const Vector3D positions[3] = { GlobalGeometry::Vertices[VertexIDs[0]].Position, GlobalGeometry::Vertices[VertexIDs[1]].Position, GlobalGeometry::Vertices[VertexIDs[2]].Position };
    const Vector3D normals [3] = { GlobalGeometry::Vertices[VertexIDs[0]].Normal , GlobalGeometry::Vertices[VertexIDs[1]].Normal , GlobalGeometry::Vertices[VertexIDs[2]].Normal };

    const Vector3D e01 = positions[1] - positions[0];
    const Vector3D e12 = positions[2] - positions[1];
    const Vector3D e20 = positions[0] - positions[2];

    const Vector3D C1 = ( normals[1] * normals[1].Dot( e01 ) - normals[0] * normals[0].Dot( e01 ) ) * Alpha;
    const Vector3D C2 = ( normals[2] * normals[2].Dot( e12 ) - normals[1] * normals[1].Dot( e12 ) ) * Alpha;
    const Vector3D C3 = ( normals[0] * normals[0].Dot( e20 ) - normals[2] * normals[2].Dot( e20 ) ) * Alpha;

    // The Pencil of M and N is Given as Mx + N

    //      a d e
    // Matrix M = d b f
    //      e f c

    //      l o p
    // Matrix N = o m q
    //      p q n

    const Real a = -T1.Dot( C3 );
    const Real l = -T2.Dot( C3 );
    const Real b = -T1.Dot( C2 );
    const Real m = -T2.Dot( C2 );
    const Real c = T1.Dot( positions[2] ) + ray.PlaneConstant1;
    const Real n = T2.Dot( positions[2] ) + ray.PlaneConstant2;
    const Real d = T1.Dot( C1 - C2 - C3 ) * 0.5;
    const Real o = T2.Dot( C1 - C2 - C3 ) * 0.5;
    const Real e = T1.Dot( C3 + e20 ) * 0.5;
    const Real p = T2.Dot( C3 + e20 ) * 0.5;
    const Real f = T1.Dot( C2 - e12 ) * 0.5;
    const Real q = T2.Dot( C2 - e12 ) * 0.5;

    // auu+bvv+c+2duv+2eu+2fv
    // luu+mvv+n+2ouv+2pu+2qv

    // Cubic Equation
    const Real coeffs[4] =
    {
        ( l*m*n + 2.0 * o*p*q ) - ( l*q*q + m*p*p + n*o*o ),
        ( a*m*n + l*b*n + l*m*c + 2.0 * (d*p*q + o*e*q + o*p*f) ) - ( a*q*q + b*p*p + c*o*o + 2.0 * (l*f*q + m*e*p + n*d*o) ),
        ( a*b*n + a*m*c + l*b*c + 2.0 * (o*e*f + d*e*q + d*p*f) ) - ( l*f*f + m*e*e + n*d*d + 2.0 * (a*f*q + b*e*p + c*d*o) ),
        ( a*b*c + 2.0 * d*e*f ) - ( a*f*f + b*e*e + c*d*d )
    };

    // Solve Cubic
    Real xs[3];
    Integer num = FunctionSolver::Cubic(coeffs, xs);
    if( 0 == num ) { return false; };

    Real x;
    Real determinant = Infinity;
    Binary flag = false;
    for(Integer i = 0; i < num; ++i)
    {
        A = a * xs[i] + l;
        B = b * xs[i] + m;
        D = d * xs[i] + o;
        if ( determinant > (D*D-A*B) ) { determinant = D*D-A*B; x = xs[i]; }
    }

    const Integer domain = ray.Direction.Domain();
    {
        A = a * x + l;
        B = b * x + m;
        D = d * x + o;

        // Avoid an Ellipsoid whose Area is Zero
        if( 0.0 < determinant )
        {
            C = c * x + n;
            E = e * x + p;
            F = f * x + q;

            // Choose A or B, whichever Suitable

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if( Abs(A) < Abs(B))
{
  // Factorizing by Using an Irreducible Equation
  // ( x y 1 ) S ( x y 1 )' = ( a1 x + b1 y + c1 )( a2 x + b2 y + c2 )
  // ( x y 1 ) S ( x y 1 )' = ( a1 x + y + c1 )( a2 x + y + c2 )
  A /= B; C /= B; D /= B; E /= B; F /= B; // B = 1.0;
  Real sqrtA = Sqrt( D*D - A );
  Real sqrtC = Sqrt( F*F - C );
  la1 = D + sqrtA;
  la2 = D - sqrtA;
  lc1 = F + sqrtC;
  lc2 = F - sqrtC;

  //if(Delta64 < Abs( (2.0*E) - (la1*lc2 + la2*lc1) ) )
  if( Abs( (2.0*E) - (la1*lc1 + la2*lc2) ) < Abs( (2.0*E) - (la1*lc2 + la2*lc1) ) )
  {
    Swap( lc1, lc2 );
  }
  for(Integer loop = 0; loop < 2; ++loop)
  {
    g = (0 == loop) ? -la1 : -la2;
    h = (0 == loop) ? -lc1 : -lc2;

    // Solve the Quadratic Equation f(y) = c0 u u + c1 u + c2 = 0
    c0 = a + (2.0 * d + b * g) * g;
    c1 = 2.0 * ( d + b * g) * h + e + f * g;
    c2 = (b * h + 2.0 * f) * h + c;

    if(0.0 < c0 && (0.0 < c1 && 0.0 < c2 || 0.0 > c2 && 0.0 > c0 + c1 + c2)) { continue; }
    if(0.0 > c0 && (0.0 > c1 && 0.0 > c2 || 0.0 < c2 && 0.0 < c0 + c1 + c2)) { continue; }

    if( 0.0000000001 > Abs(c0) )
    {
      if( 0.0000000001 < Abs(c1))
      {
        u = -c2 / c1; v = g * u + h; w = 1.0 - (u + v);
        if(0.0 <= u && 0.0 <= v && 0.0 <= w)
        {
          param = (EvaluatePhongTessellation( u, v, w, positions, normals, domain) - ray.Position[domain]) / ray.Direction[domain];
          if( Epsilon < param && param < ray.Depth - Epsilon && param < depth )
          {
            barycentric_coord = Vector3D(u, v, w);
            depth = param;
            flag = true;
          }
        }
      }
    }
  }
}
else
{
  Real tmp0, tmp1;
  discriminant = (c1 * c1) - 4.0 * (c0 * c2);
  if( 0.0 <= discriminant )
  {
    FunctionSolver::Quadratic( c0, c1, c2, tmp0, tmp1 );

    // with Line 1
    u = tmp0; v = g * u + h; w = 1.0 - (u + v);
    if(0.0 <= u && 0.0 <= v && 0.0 <= w)
    {
      param = (EvaluatePhongTessellation( u, v, w, positions, normals, domain) - ray.Position[domain]) / ray.Direction[domain];
      if( Epsilon < param && param < ray.Depth - Epsilon && param < depth )
      {
        barycentric_coord = Vector3D(u, v, w);
        depth = param;
        flag = true;
      }
    }

    // with Line 2
    u = tmp1; v = g * u + h; w = 1.0 - (u + v);
    if(0.0 <= u && 0.0 <= v && 0.0 <= w)
    {
      param = (EvaluatePhongTessellation( u, v, w, positions, normals, domain) - ray.Position[domain]) / ray.Direction[domain];
      if( Epsilon < param && param < ray.Depth - Epsilon && param < depth )
      {
        barycentric_coord = Vector3D(u, v, w);
        depth = param;
        flag = true;
      }
    }
  }
}
}
else
{
  // Factorizing by Using an Irreducible Equation
  // ( x y 1 ) S ( x y 1 )' = ( a1 x + b1 y + c1 )( a2 x + b2 y + c2 )
  // ( x y 1 ) S ( x y 1 )' = ( x + b1 y + c1 )( x + b2 y + c2 )
  B /= A; C /= A; D /= A; E /= A; F /= A; // A = 1.0;
  Real sqrtB = Sqrt( D*D - B );

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Real sqrtC = Sqrt( E*E - C );
lb1 = D + sqrtB; // lb = D +- SqrtB
lb2 = D - sqrtB;
lc1 = E + sqrtC; // lc = E +- SqrtC
lc2 = E - sqrtC;
//if(Delta64 < Abs( (2.0*F) - (lb1*lc2 + lb2*lc1) ) )
if(Abs( (2.0*F) - (lb1*lc1 + lb2*lc2) ) < Abs( (2.0*F) - (lb1*lc2 + lb2*lc1) ) )
{
    Swap( lc1, lc2 );
}
for(Integer loop = 0; loop < 2; ++loop)
{
    g = (0 == loop) ? -lb1 : -lb2;
    h = (0 == loop) ? -lc1 : -lc2;

    // Solve the Quadratic Equation f(y) = c0 v v + c1 v + c2 = 0
    c0 = b + (2.0 * d + a * g) * g;
    c1 = 2.0 * ( (d + a * g) * h + f + e * g );
    c2 = (a * h + 2.0 * e) * h + c;

    if(0.0 < c0 && (0.0 < c1 && 0.0 < c2 || 0.0 > c2 && 0.0 > c0 + c1 + c2)) { continue; }
    if(0.0 > c0 && (0.0 > c1 && 0.0 > c2 || 0.0 < c2 && 0.0 < c0 + c1 + c2)) { continue; }

    if( 0.0000000001 > Abs(c0) )
    {
        if( 0.0000000001 < Abs(c1) )
        {
            v = -c2 / c1; u = g * v + h; w = 1.0 - (u + v);
            if( 0.0 <= u && 0.0 <= v && 0.0 <= w )
            {
                param = (EvaluatePhongTessellation( u, v, w, positions, normals, domain ) - ray.Position)[domain] / ray.Direction[domain];
                if( Epsilon < param && param < ray.Depth - Epsilon && param < depth )
                {
                    barycentric_coord = Vector3D(u, v, w);
                    depth = param;
                    flag = true;
                }
            }
        }
    }
}
else
{
    Real tmp0, tmp1;
    discriminant = (c1 * c1) - 4.0 * (c0 * c2);
    if( 0.0 <= discriminant )
    {
        FunctionSolver::Quadratic( c0, c1, c2, tmp0, tmp1 );

        // with Line 1
        v = tmp0; u = g * v + h; w = 1.0 - (u + v);
        if( 0.0 <= u && 0.0 <= v && 0.0 <= w )
        {
            param = (EvaluatePhongTessellation( u, v, w, positions, normals, domain ) - ray.Position)[domain] / ray.Direction[domain];
            if( Epsilon < param && param < ray.Depth - Epsilon && param < depth )
            {
                barycentric_coord = Vector3D(u, v, w);
                depth = param;
                flag = true;
            }
        }
        // with Line 2
        v = tmp1; u = g * v + h; w = 1.0 - (u + v);
        if( 0.0 <= u && 0.0 <= v && 0.0 <= w )
        {
            param = (EvaluatePhongTessellation( u, v, w, positions, normals, domain ) - ray.Position)[domain] / ray.Direction[domain];
            if( Epsilon < param && param < ray.Depth - Epsilon && param < depth )
            {
                barycentric_coord = Vector3D(u, v, w);
                depth = param;
                flag = true;
            }
        }
    }
}
}
}
}
}
}
}
}
}
}
}
return flag;
}

```